

PATENT ABSTRACTS OF JAPAN

(11)Publication number : 10-217161

(43)Date of publication of application : 18.08.1998

(51)Int.Cl.

B25J 5/00

(21)Application number : 09-033175

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(22)Date of filing : 31.01.1997

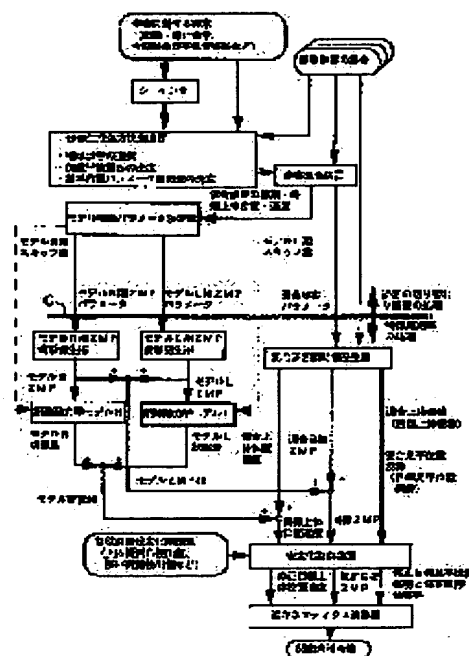
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(54) WALKING ATTITUDE PRODUCING DEVICE OF MOBILE ROBOT WITH LEGS

(57)Abstract:

PROBLEM TO BE SOLVED: To provide a walking attitude producing device for a leg type mobile robot, in particular a two-foot walking robot, with which it is practicable to produce any desired walking attitude to enable continuous walking for a long period.

SOLUTION: Two walking attitudes are produced for one step, and if there is any discontinuous quantity at their boundary such as the position and/or speed of the upper body of robot, or ZMP(zero moment point), the input obtained on the basis of the inverse number of the discontinuous quantity is given to a perturbational dynamic model so as to cancel the discontinuous quantity, and the produced walking attitude is corrected with the output, and a walking attitude is accomplished which has a continuous robot upper body position and/or speed or ZMP even at the boundary.



LEGAL STATUS

[Date of request for examination]

16.05.2003

[Date of sending the examiner's decision of rejection]

[Kind of final disposal of application other than the examiner's decision of rejection or application converted registration]

[Date of final disposal for application]

[Patent number]

[Date of registration]

[Number of appeal against examiner's decision of rejection]

[Date of requesting appeal against examiner's decision of rejection]

[Date of extinction of right]